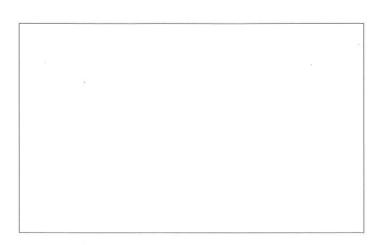


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Narrow Pipe Driving Method

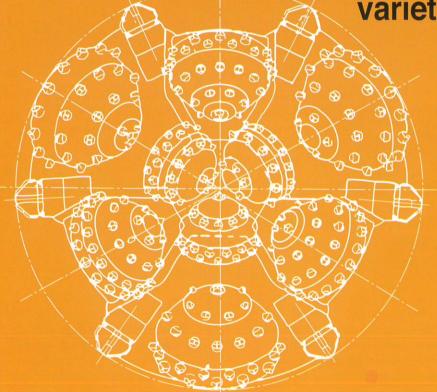
ACEMOLE

Slurry Pressure Method /
Single-Process Method
(Pressurized Slurry Removal Method)

(Nominal Diameter 250-700mm)

DL-C DL-N

Realizing long distance and curved driving through a wide variety of soil conditions



Realizing long distance and curved driving through a wide variety of soil conditions

With the next generation of facilities such as sewage pipes being installed to support our day-to-day lives, there is a call for more environmentally friendly pipe driving technology.

The ACEMOLE DL Method meets these needs with a slurry pressurebased pressurized transport method for excavation and slurry discharge that employs unique position detection mechanisms, enabling both long distance and curved driving with a high degree of precision through a wide variety of soil conditions from soft ground to bedrock.





Sharp curve with a curve radius of 45m

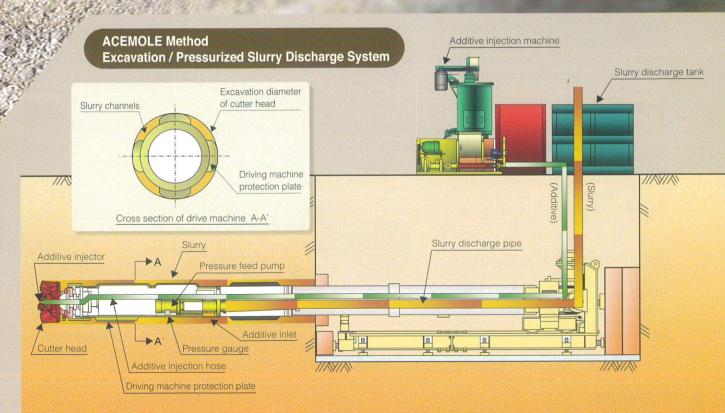
Excavation and slurry discharge system of ACEMOLE method The pressurized discharge system injects additive into the excavation soil, turning it into mud (slurry).

The slurry is then pumped to the pit, where it is discharged.

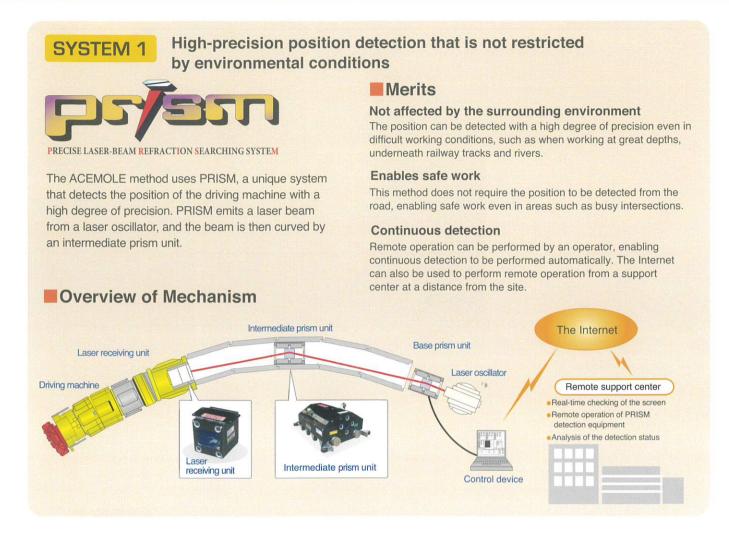
Additive is discharged from the end and injected into the working face as the cutter head rotates. Excavated soil is turned into fluid, water-stopping mud (slurry).

Soil that has been turned into slurry is sent along the contours of the driving machine to the rear portion, while part of this is removed from the starting pit under pressure by the pressure feed pump via the slurry discharge pipe.

The slurry inlet volume is controlled so that some of the slurry is left in the ground. This prevents the working face and shaft wall from collapsing and reduces thrust due to the lubricating effect of the slurry.



Position Detection Mechanisms



SYSTEM 2

Unique mechanisms are combined for accurate position detection

Electromagnetic method and fluid pressure differential method The conventional laser target method is combined with ACEMOLE's

unique electromagnetic method and fluid pressure differential method to enable accurate position detection even in difficult working conditions such as long-distance and curved driving.

Merits

Enables highly precise position detection

The mechanism enables detection to be performed with Induced magnetic uniform precision even in difficult working conditions such as long-distance and curved driving.

Easy to operate

This unique technology makes it easy to operate when performing position detection.

Overview of Mechanism

Electromagnetic method

Horizontal position detection

An electromagnetic method makes it possible to detect the horizontal position of the driving machine (maximum applicable soil coverage: 6-8m).

DL-N (Standard Type)

The standard type enables both long distance and curved driving using a standard pipe.

Type & Diameter of pipe	HP : φ250 - 350	HP : ф400 - 500	HP : ф600 - 700
Model	DL35-N	DL50-N	DL70-N

Applicable models and applicable types of pipe

Applicable	Standard Type Segmented Driving Type			DL35-N			DL50-N		DL7	0-N
models			gmented Driving Type DL35-C			DL50-C			DL70-C	
	Reinforced concrete pipes Steel pipes		ф250	ф300	ф350	ф400	ф450	ф500	ф600	ф700
			Steel pipes	Steel pipes φ	Steel pipes	ф400	ф400 ф450	ф500 ф55	ф550	550 ф600
Applicable	Resin concrete pipes	RT mode	ф250	ф300	ф350	ф400	ф450	ф500	ф600	ф700
types of		RM mode	ф290	ф340	ф390	ф440	ф490	ф540	ф650	φ760
pipe		RS mode	ф300	ф350	ф400	ф450	ф500	_	ф700	-
	The measuren	nents for	4200		ф350	ф400	Ф500		ф600	
	ductile cast-iron pipes		ф300 —	ψ350	ф450	φουσ	_	ф700) 	

Explanation of Models

[DL35-C] 2.0m		
Type & Diameter of pipe HP : φ250	- 350 HP : φ400) - 500 HP : φ600 - 70

*The measurements for ductile cast-iron pipes are for t	he I type T mod	del.	
*For information relating to other types of pipe, please	contact us.		

ACEMOLE 4 **ACEMOLE**

Base fluid pressure

Laser oscillator

Induced magnetic

Lines of

Pressure sensor

This system detects the vertical position of the driving

machine according to the fluid pressure difference.

Fluid pressure differential method:

Vertical position detection

Range of Application: DL-C (Segmented Driving Type)

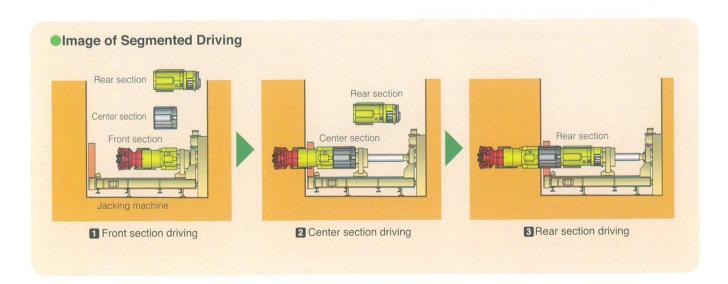
Soil Conditions (Segmented Driving Type)

Legend ○: Opera	ation possi	ble	
△: TBD (additional	construction,	etc.)

Soil Quality Range			Soil	DL35 D	L50 DL70		
		Gravel/Rock Conditions			Application	Cutter Type	
Classification	Name	N Value	Max. Gravel/Rock Diameter	Percentage of Gravel Content	Unconfined Compression Strength (qu)	Application	Cutter Type
	Cohesive	N<1 *1				Δ	
	Soil	1≦N<2*1			·	0	
Standard	Sandy Soil	N<4 *1			=	Δ	
Soil [A]	Cohesive Soil	2≦N<50	2				Spoke Type
	Sandy Soil	4≦N<50				0	
	Pebble	4≦N<50	Smaller than 20mm	Smaller than 10%			
Hard Soil [B]	Soft Rock, Hard Clay	N≧50			Smaller than 10MN/m²	0	
Hard Soli [b]	Pebbles		Smaller than 75mm	Smaller than 30%			要表 美
Pebbles [C]	Pebbles		Smaller than 200mm	Smaller than 60%	Smaller than 120MN/m²	0	Roller Type II
Gravel/	[D]		Smaller than 400mm	Smaller than 80%	Smaller than 150MN/m²	0	Holler Type II
Rocky Soil	[E]		Smaller than 800mm	Smaller than 90%	Smaller than 250MN/m²	<u></u> *2	
	[G]				10 <qu≦20mn m²<="" td=""><td></td><td></td></qu≦20mn>		
	[H]				20 <qu≦40mn m²<="" td=""><td></td><td>Roller Type III</td></qu≦40mn>		Roller Type III
Bedrock	[J]				40 <qu≦60mn m²<="" td=""><td>0</td><td></td></qu≦60mn>	0	
	[K]				60 <qu≦80mn m²<="" td=""><td></td><td></td></qu≦80mn>		
	[L]				80 <qu≦100mn m²<="" td=""><td></td><td></td></qu≦100mn>		
Special soil is by the above			individual research onstruction method		dditional construction is red.	necessary	

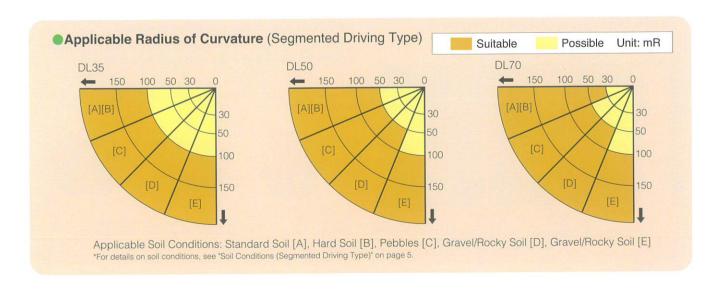
^{*1} Applicable only for straight lines.

^{*3} The cutter head type is only a guide for application, and may change depending on conditions such as the soil conditions and driving length.



Applicable Driving Length Maximum recorded Applicable (Segmented Driving Type) Driving Length driving length *3 **Driving Length** Applicable Compression Model Diameter Soil Condition 150 Standard Soil [A] Hard Soil [B] qu≦120 Pebbles [C] qu≦150 Gravel/Rocky Soil[D] qu≦150 Gravel/Rocky Soil[E] qu≦200 250 - 350 DL35-C qu≦250 10<qu≦20 Bedrock[G] 20<qu≦40 Bedrock[H] Bedrock[J] 40<qu≦60 60<qu≦80 Bedrock[K] 80<qu≦100 Bedrock[L] Standard Soil [A] Hard Soil [B] Pebbles [C] qu≦120 qu≦150 Gravel/Rocky Soil[D] qu≦150 DL50-C 400 - 500 Gravel/Rocky Soil[E] qu≦200 qu≦250 DL70-C 600 - 700 10<qu≦20 Bedrock[G] 20<qu≦40 Bedrock[H] 40<qu≦60 Bedrock[J] Bedrock[K] 60<qu≦80 80<qu≦100 Bedrock[L]

^{*3} The figures for maximum recorded driving length are for starting pits with a diameter of φ2,500mm.



^{*2} Contact us for details on application of the DL35 in gravel/rocky soil [E], as the applicable operation depends on conditions such as the soil conditions and driving length.

^{*1} Please note that the driving length differs according to various conditions, even within the standard range. Please contact us for details.

^{*2} For straight-line driving lengths over 100m, equipment such as oil cooling equipment and suction equipment needs to be used to maintain the precision of position detection by laser targeting.

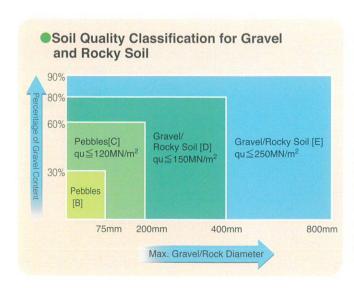
Range of Application: DL-N (Standard Type)

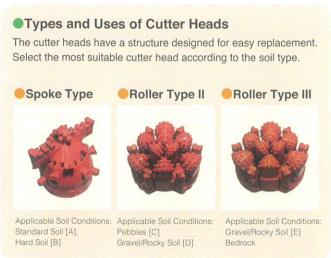
Soil Condition (Standard Type)

Soil Quality Range			Soil	DL35 DL50 DL70			
			0	Gravel/Rock Co	nditions		
Classification	Name	N Value	Max. Gravel/Rock Diameter	Percentage of Gravel Content	Unconfined Compression Strength (qu)	Application	Cutter Type
	Cohesive	N<1 *1				Δ	
	Soil	1≦N<2*1				0	
Standard	Sandy Soil	N<4 *1				Δ	
Soil [A]	Cohesive Soil	2≦N<50					Spoke Type
	Sandy Soil	4≦N<50				0	
	Pebble	4≦N<50	Smaller than 20mm	Smaller than 10%			
Hard Soil [B]	Soft Rock, Hard Clay	N≧50			Smaller than 10MN/m²	0	
mara com [D]	Pebbles		Smaller than 75mm	Smaller than 30%			
Pebbles [C]	Pebbles		Smaller than 200mm	Smaller than 60%	Smaller than 120MN/m²	0	Dallas Taras III
Gravel/	[D]		Smaller than 400mm	Smaller than 80%	Smaller than 150MN/m²	0	Roller Type II
Rocky Soil	[E]		Smaller than 800mm	Smaller than 90%	Smaller than 250MN/m²	○ *2	
	[G]				10 <qu≦20mn m²<="" td=""><td></td><td></td></qu≦20mn>		
	[H]				20 <qu≦40mn m²<="" td=""><td></td><td>Roller Type III</td></qu≦40mn>		Roller Type III
Bedrock	[J]				40 <qu≦60mn m²<="" td=""><td>0</td><td></td></qu≦60mn>	0	
	[K]				60 <qu≦80mn m²<="" td=""><td></td><td></td></qu≦80mn>		
	[L]				80 <qu≦100mn m²<="" td=""><td></td><td></td></qu≦100mn>		
Special soil n			ndividual research nstruction method		ditional construction is red.	ecessary	

^{*1} Applicable only for straight lines.

^{*3} The cutter head type is only a guide for application, and may change depending on conditions such as the soil conditions and driving length.

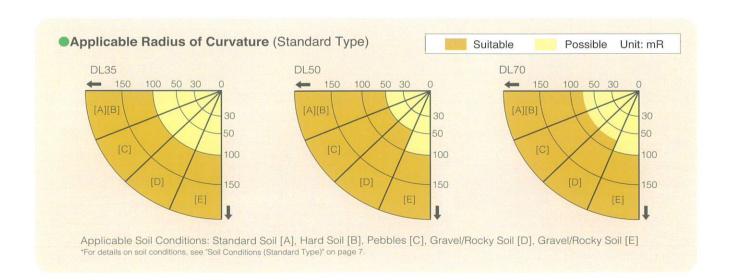






^{*1} Please note that the driving length differs according to various conditions, even within the standard range. Please contact us for details.

^{*2} For straight-line driving lengths over 100m, equipment such as oil cooling equipment and suction equipment needs to be used to maintain the precision of position detection by laser targeting.



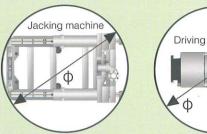
ACEMOLE 8

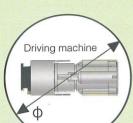
^{*2} Contact us for details on application of the DL35 in gravel/rocky soil [E], as the applicable operation depends on conditions such as the soil conditions and driving length

Pit Dimensions

DL-C

Segmented Driving / Starting pit and Arriving pit





Starting pit dimensions

limensions of inner space with water stop installed) (unit: mm)

Nominal diameter	Starting in one direction	Starting in both directions
ф250 - 300	ф2,000	ф2,500
ф350 - 500	ф2,500	ф2,500
ф600 - 700	ф2,500	ф3,000

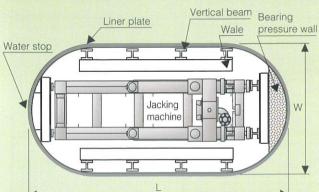
Arriving pit dimensions

mensions of inner space with water stop installed) (unit: mm)

Nominal diameter	Arriving in one direction	Arriving in both directions
ф250 - 350	ф1,200	ф1,500
ф400 - 500	ф1,500	ф1,800
ф600 - 700	ф1,800	ф2,200

DL-N

■With liner plate



Starting	pit	dimension	5
otarting	Pir	difficitoron	٠

(unit: mm)

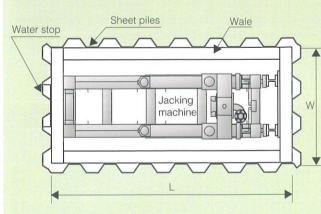
Nominal diameter	Starting in o	ne direction	Starting in both directions	
Norminal diameter	L	W	L	W
ф250 - 350	4,070	2,500	4,541	2,500
ф400 - 500	5,797	2,500	5,797	2,500
ф600 - 700	5,826	3,000	5,826	3,000

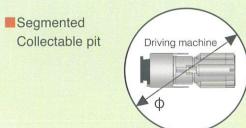
Arriving pit dimensions

(unit: mm

Nominal diameter	Arriving in o	one direction	Arriving in both directions		
Northinal diameter	L	W	L	W	
ф250 - 350	3,884	2,000	4,198	2,000	
ф400 - 500	4,198	2,000	4,512	2,000	
ф600 - 700	4,041	2,000	4,355	2,000	

■With sheet pile steel retaining structure





Starting pit dimensions

(unit: mm)

Nominal diameter	Starting in one direction		Starting in both directions	
	L	W	L	W
ф250 - 350	4,800	2,800	4,800	2,800
ф400 - 500	5,600	2,800	5,600	2,800
ф600 - 700	5,600	3,200	5,600	3,200

Arriving pit dimensions

(unit: n

Arriving pit dimensions				(unit min
Nominal diameter	Arriving in one direction		Arriving in both directions	
	L	W	L	W
ф250 - 350	4,000	2,000	4,400	2,000
ф400 - 500	4,400	2,400	4,800	2,400
ф600 - 700	4,400	2,400	4,800	2,400

Segmented Collectable pit dimensions

(dimensions of inner space with water stop installed) (unit: mm)

Nominal diameter	Arriving in one direction	Arriving in both directions	
ф250 - 350	ф1,800	ф2,000	
ф400 - 500	ф2,000	ф2,300	
ф600 - 700	ф2,000	ф2,400	

^{*} Please note that the pit dimensions differ according to various conditions. Please contact us for details.

Examples of Work

1 Long-distance curved driving across a distance of over 250m

Type & Diameter of pipe	Reinforced concrete pipe for driving (nominal diameter: 450mm)
Driving length	Zone 1: 190.6m (S-curve: R=200m) Zone 2: 271.4m (Single curve: R=80m)
Soil	Cohesive Soil - Sand
Other	As a thrust reduction measure, friction-reducing materials were injected from the pithead and rear pipe and applied to the outside of the pipe to be driven. As a result, driving was completed with less than the designed thrust.





2 Long-distance driving under a river using a PRISM

Type & Diameter of pipe	Reinforced concrete pipe for driving (nominal diameter: 500mm)
Driving length	245.1m
Other	A PRISM was used to drive under the river at a great depth, enabling the driving to be carried out with a high degree of precision.



